

TECHNICAL SPECIFICATIONS

Extra long range laser scanner combined with a high resolution digital panoramic camera.

Tough > Reliable > Proven



GENERAL

Size 455h x 246d x 378w Weight 14kg, without battery

Battery Interchangeable, LiO 2.5 hours operation

Levelling 20" (internal compensator)

Constant operating temp. 0° to +50°C

(Short exposure* -40° to +50°C)

Storage temperature -40° to +70°C

Compass[¶] $\pm 1^{\circ}$ Reliability ISO 9022

Protection class IP-65 (IEC 60529)

Data recorder Wireless ruggedised PC plus onboard USB

MountingStandard tribrach mountGPS mountExternal 5/8" UNC thread

Carry case Customised case

SCANNER

Maximum range[†] >2000m

Up to 1400m, reflectivity >80% Up to 1000m, reflectivity >40% Up to 500m, reflectivity >10%

 $\begin{array}{ll} \mbox{Minimum range} & 2.5\mbox{m} \\ \mbox{Range accuracy‡} & 8\mbox{mm} \\ \mbox{Repeatability} & \pm 8\mbox{mm} \\ \mbox{Exit aperture} & < 8\mbox{mm} \\ \end{array}$

Beam divergence0.25mrad (1/e^2 radius)Acquisition rate8800 points per secondProduct laser classClass 1 IEC60825-1:2007

Wavelength Near IR
Intensity measurement Yes

Angular step selectable 0.2° to 0.0125°

Angular accuracy§ 0.01°
Angular measurement res. 0.001°

Angular scanning range 80° vertical, 360° horizontal



DIGITAL CAMERA (Included in system)

Type Line scanning digital panoramic camera

Pixel resolution 70 megapixel

Angular range 80° vertical, 360° horizontal

Acquired During laser scan Exposure control User definable

Lens Nikon 20mm f/2.8D, with filter Image render method Corrected image automatically

rendered to scan in I-Site Studio

Depth of field 3m to infinity

TELESCOPE (Included in system)

Angular range 80° vertical, 360° horizontal

Focal range 5m to infinity

Focus control Electronic motorised focus

Objective aperture 28mm

Magnification 14x

Reticule Crosshair

Field of view 3° in field

Resolving power ±5"

Minimum azimuth step 3.6"

Laser pointer 650nm red laser (Class 1)



 $^{^{\}star}$ Time to perform 20 minute scan. Contact Maptek for further assistance

 $[\]P$ Assumes no metallic objects or magnetic field inteference

 $[\]dagger$ Under normal operating conditions. Based on flat normal returns and good atmospheric conditions

[‡] Under Maptek test conditions

[§] Pointing accuracy